

A STUDY OF THE COMPOSITION OF ULTRA-HIGH-ENERGY COSMIC RAYS USING THE HIGH-RESOLUTION FLY’S EYE

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ABSTRACT

The composition of ultra-high-energy cosmic rays is measured with the High Resolution Fly’s Eye cosmic-ray observatory data using the X_{\max} technique. Data were collected in stereo between 1999 November and 2001 September. The data are reconstructed with well-determined geometry. Measurements of the atmospheric transmission are incorporated in the reconstruction. The detector resolution is found to be 30 g cm^{-2} in X_{\max} and 13% in energy. The X_{\max} elongation rate between $10^{18.0}$ and $10^{19.4}$ eV is measured to be $54.5 \pm 6.5(\text{stat}) \pm 4.5(\text{sys}) \text{ g cm}^{-2}$ per decade. This is compared with predictions using the QGSJet01 and SIBYLL 2.1 hadronic interaction models for both protons and iron nuclei. CORSIKA-generated extensive air showers are incorporated directly into a detailed detector Monte Carlo program. The elongation rate and the X_{\max} distribution widths are consistent with a constant or slowly changing and predominantly light composition. A simple model containing only protons and iron nuclei is compared with QGSJet and SIBYLL. The best agreement between the model and the data is for 80% protons for QGSJet and 60% protons for SIBYLL.

Subject headings: acceleration of particles — cosmic rays — large-scale structure of universe

1. INTRODUCTION

The cosmic-ray (CR) spectrum follows a power law that exhibits several interesting features. A break (known as the knee) in the power law from index -2.7 to index -3.0 occurs near 10^{15} eV. A similar break (the second knee) from index -3.0 to -3.3 has been reported near $10^{17.7}$ eV (Abu-Zayyad et al. 2001a; Bird et al. 1993, 1995; Pravdin et al. 1999; Glushkov et al. 2003; Nagano et al. 1984; Lawrence et al. 1991) and is followed by a rise to an index of -2.7 (the ankle) near $10^{18.6}$ eV. The spectrum appears to continue until $10^{19.8}$ eV.

Changes in spectral index at various energies could be produced by a gradual decrease in efficiency with the energy of a source (e.g., Galactic supernovae), leakage from an area of magnetic confinement (the Galactic leaky-box model), the ap-

pearance of flux from new sources that begin to dominate at higher energies (extragalactic CRs), and thresholds of inelastic interactions between CR protons and the cosmic microwave background radiation (e^+e^- and pion production, the GZK effect; Greisen 1966; Zatespin & Kuz’min 1966). It has also been suggested that the hadronic interaction of the CR with the atmosphere undergoes changes above certain energies that would affect the measured energy of the CR and hence produce an apparent change in the power-law index (Kazanas & Nicolaidis 2003). A knowledge of CR composition as a function of energy would be invaluable in sorting out these effects.

High-energy CRs have long been known to be charged nuclei (Clay 1927), but determining the chemical composition at energies greater than 10^{15} eV is especially difficult because of the low flux. The High Resolution Fly’s Eye cosmic-ray observatory (HiRes) has an aperture large enough ($3 \times 10^2 - 5 \times 10^3 \text{ km}^2$ sr), but it observes the extensive air shower (EAS) produced by the particle rather than detecting the primary itself, and thus, we must use an indirect method to study the composition.

The distribution of positions of shower maxima (X_{\max}) in the atmosphere has been shown to be sensitive to the composition of CRs (Heitler 1944). It is well known that for any particular species of nucleus the position of shower maximum deepens with increasing energy as the logarithm of the energy. The slope $d(X_{\max})/d(\log E)$ is known as the elongation rate (ER; Linsley 1977b).

While the details depend on the hadronic model assumed, all modern hadronic models give approximately the same ER (between 50 and 60 g cm^{-2} per decade of energy, independent

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of particle species) and agree within about 25 g cm^{-2} on the absolute position of the average shower X_{max} at a given energy for a given species. The sensitivity of the X_{max} method to composition comes from the fact that the mean X_{max} for iron and protons is different by about 75 g cm^{-2} , independent of hadronic model, with protons producing deeper showers with larger fluctuations. A change in the composition from heavy to light would then result in a larger ER than $50\text{--}60 \text{ g cm}^{-2}$ per decade, and a change from light to heavy would lead to a lower and even negative ER.

Previous experiments (stereo Fly's Eye [Bird et al. 1993] and HiRes prototype–Michigan Muon Array [MIA; Abu-Zayyad et al. 2000b]) have shown evidence for an ER of $80\text{--}90 \text{ g cm}^{-2}$ per decade in the energy range from 10^{17} to $10^{18.5}$ eV. No significant information from air fluorescence experiments has been hitherto available on the behavior of the ER near 10^{19} eV and above.

The general dependence of X_{max} on energy can be seen in a simple branching model in which $N_{\text{max}} \propto E_0$ and $X_{\text{max}} \propto \ln E_0$ (Gaisser 1990; Heitler 1944). In this model if the primary particle is a nucleus, the shower is assumed to be a superposition of subshowers, each initiated by one of the A independent nucleons. The primary energy must be divided among the A constituents, so in this case $X_{\text{max}} \propto \ln(A/E_0)$. A more complete discussion leads to Linsley's expression for the ER,

$$\text{ER} = (1 - B)K\lambda \left(1 - \frac{d \log \langle A \rangle}{d \log E_0} \right), \quad (1)$$

where K is a constant, λ is the collision length, and B expresses the dependence of ER on the hadron–air nucleus interactions (Gaisser et al. 1979; Linsley 1977a). It includes both the energy dependence of the cross section (and thus λ) and the energy dependence of the multiplicity and inelasticity (Heck 2001; Linsley & Watson 1981; Feynman 1969).

The technique for extracting the CR composition used in this paper reduces to comparing the X_{max} distribution of the data after appropriate cuts that guarantee good resolution in this variable, with simulated data generated with either a proton or iron parent particle. The simulated data are the result of a detailed detector Monte Carlo and include all the reconstruction uncertainties.

2. THE HiRes DETECTOR

HiRes has two sites on the US Army's Dugway Proving Ground in the West Desert of Utah, about 90 miles from Salt Lake City. The first site, HiRes-1, is on Little Granite Mountain, the site of the original Fly's Eye detector. HiRes-2 is 12.6 km to the southwest on Camel's Back Ridge. Dugway was chosen for its clean atmosphere and low light pollution. Each site is on a hill, above the bulk of most haze in the atmosphere. The two sites gather data independently, and the data can be analyzed from each site in monocular mode or together in stereo mode. Results from a monocular analysis of the spectrum have been published (Abbasi et al. 2004a, 2004b). The accurate determination of the shower geometry is an essential first step to determining the shower profile, which gives the energy of the primary Ultra-High-Energy Cosmic Ray (UHECR) and the X_{max} of the shower. This work presents results from stereo analysis, which has an obvious advantage in determining the shower geometry and hence better resolution in energy and X_{max} .

HiRes is the realization of an extension of the method pioneered by the original Fly's Eye experiment (Baltrusaitis et al. 1985). As a UHECR-initiated EAS propagates through the

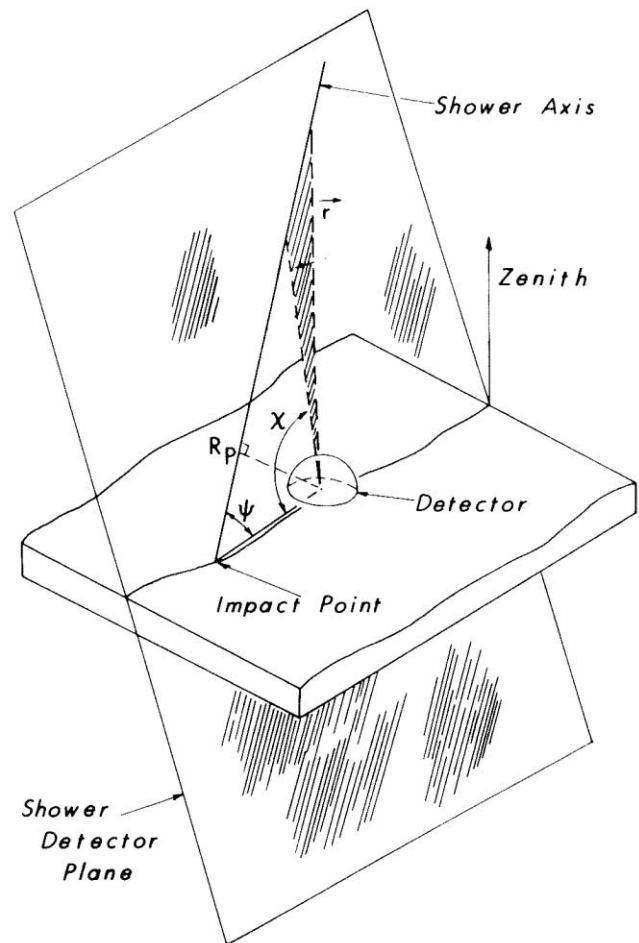


FIG. 1.—SDP. The point of the detector and the line of the shower define a plane.

atmosphere, the charged particles excite nitrogen molecules, which fluoresce. The fluorescence yield and its spectrum have both been measured (Bunner 1967; Kakimoto et al. 1996). The fluorescence yield is about $5 \text{ photons particle}^{-1} \text{ m}^{-1}$. The photons, mostly of wavelength $300\text{--}400 \text{ nm}$, propagate isotropically from the shower core, with the number of photons coming from a slice of the shower proportional to the number of charged particles in that slice. In addition to air fluorescence, Cerenkov light is produced by shower particles. The Cerenkov cone in air is 2.5° , and the resultant light angular distribution, reflecting the multiple scattering of electrons, is strongly beamed forward along the EAS axis. Some of this light, however, scatters at larger angles into the detector and needs to be subtracted from the total signal.

Air fluorescence detectors gather the photons and focus them onto arrays of photomultiplier tubes (PMTs). Each PMT views a solid angle of the sky, and a composite view is recovered when the images from the constituent mirrors are combined.

The HiRes Prototype detector, results from which are also summarized in this paper, was located on Little Granite Mountain (Abu-Zayyad et al. 2000a). The prototype detector viewed from 3° to 70° in elevation and had an azimuthal coverage that overlooked the MIA experiment 3.4 km away. Coincident hybrid data were collected from 1993 to 1996. Results on CR composition near 10^{17} eV were published in Abu-Zayyad et al. (2000b).

In 1997, the aperture for events at the highest energies was optimized by redeploying the telescopes in a ring with full 360°

TABLE 1
QUALITY CUTS

Parameter	Cut
Minimum viewing angle (both sites).....	10
Minimum opening angle between SDPs.....	5
Individual site fit χ^2	20
Global fit χ^2	15
Timing fit X_{\max} - global fit X_{\max}	500
HiRes-1 fit X_{\max} - HiRes-2 fit X_{\max}	500
Geometric uncertainty in individual site fit.....	400
Geometric uncertainty in global fit.....	200
Bracketing X_{\max}	X_{\max} within 60 of viewed track

NOTE.—Angles are in degrees, χ^2 values are unitless, and X_{\max} values are in g cm^{-2} .

azimuthal coverage and 3° – 17° elevational coverage (Abbasi et al. 2004a). HiRes-1 began taking data in 1997 May, and the ring was completed in 1998 March.

HiRes-2 has two rings, giving complete azimuthal coverage with an elevation coverage from 3° to 31° (Boyer et al. 2002). This analysis uses data from 1999 November, when HiRes-2 became completely operational, to 2001 September.

2.1. Survey and Calibration

The basic HiRes element is a telescope consisting of a mirror of area 5.2 m^2 with an associated cluster of 256 PMTs and data acquisition electronics. The PMT cluster is placed at a distance from the mirror that optimizes the spot size (Simpson 2001). When we take the cluster obscuration into account, the effective area of each mirror is 3.72 m^2 (Abbasi et al. 2004a). The pointing directions of the individual telescopes were surveyed at installation and are checked periodically by observing signals produced by stars (Bergman et al. 2001; Sadowski et al. 2002).

The primary tool for the calibration of PMT sensitivity is a xenon flash lamp mounted in a portable housing that can be moved from telescope to telescope. It is placed in the center of the mirror, illuminating the cluster directly. The lamp's output has been measured to be stable to within one-third of 1% flash-

to-flash and within 2% over the course of a night (Jones et al. 1999, 2001).

To monitor the PMT response on a nightly basis, each site has a frequency-tripled YAG laser that delivers light at 355 nm to each PMT cluster via quartz optical fibers. One fiber is routed to the center of each mirror, and one to each side of each PMT cluster. The mirror-mounted fibers illuminate the cluster directly, allowing the tube response to be monitored, whereas the cluster-mounted fibers illuminate the mirrors so mirror reflectivity can be tracked (Girard et al. 2000; Archbold et al. 2001).

3. ATMOSPHERIC CORRECTIONS

Photons from an EAS travel through the atmosphere to reach the telescopes, and understanding light transmission through the atmosphere is vital. The atmosphere can be considered a mix of molecules and aerosols. Rayleigh scattering from molecules is well understood, as is the atmospheric density profile. Scattering from aerosols varies with the aerosol content of the air and must be measured. We characterize the aerosol scattering by the horizontal aerosol extinction length, L^h , the vertical aerosol optical depth, VAOD, and the angular dependence of the scattering cross section (the phase function). Lasers with steerable beams, located at both HiRes-1 and HiRes-2 sites, are used to sweep the HiRes aperture and determine the horizontal

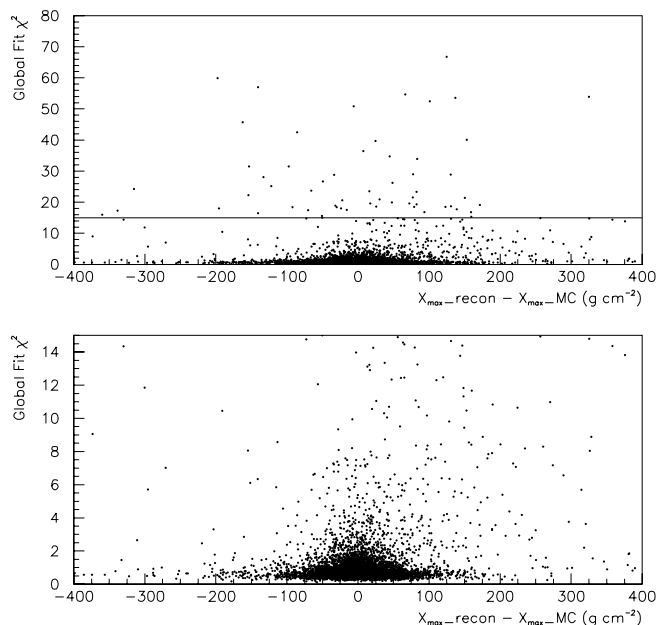


FIG. 2.—Global fit χ^2 for reconstructed Monte Carlo events. *Top*, Cut at $\chi^2 = 15$ (horizontal line); *bottom*, expanded view of the region remaining after the cut.

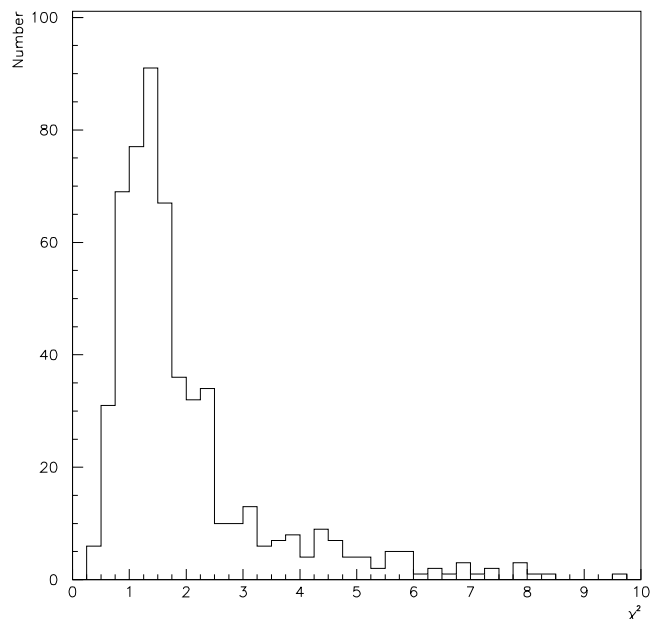


FIG. 3.—Global χ^2 fit for the data. After all cuts, none of the data had $\chi^2 > 10$.

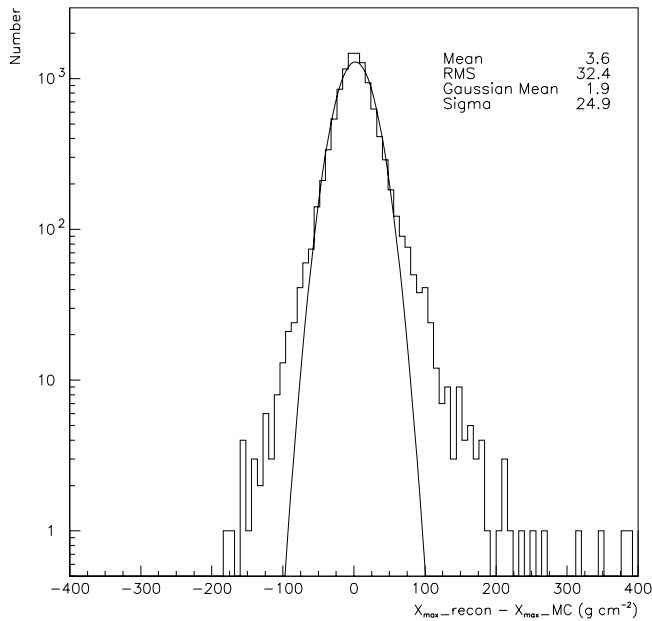


FIG. 4.— X_{\max} resolution of the detector after all cuts, as determined by the detector simulation. X_{\max} -MC is the thrown X_{\max} of the shower, and X_{\max} -recon is the reconstructed X_{\max} .

extinction length, VAOD, and phase function (Roberts et al. 2001; Wiencke et al. 2001a). A database of the hourly parameterizations of the atmosphere is used in Monte Carlo and to reconstruct every event for which it is available (Reil 2002). For the final data set, about three-quarters of the events were reconstructed with atmospheric parameters from the hourly database, and the remainder were reconstructed with the average values (see § 4.6).

The laser tracks also give an indication of clouds in the aperture. The track of a laser hitting a cloud mushrooms out, giving a shorter, wider signature.

Other tools for understanding the clarity of the atmosphere include operator observations, infrared cloud monitors, and xe-

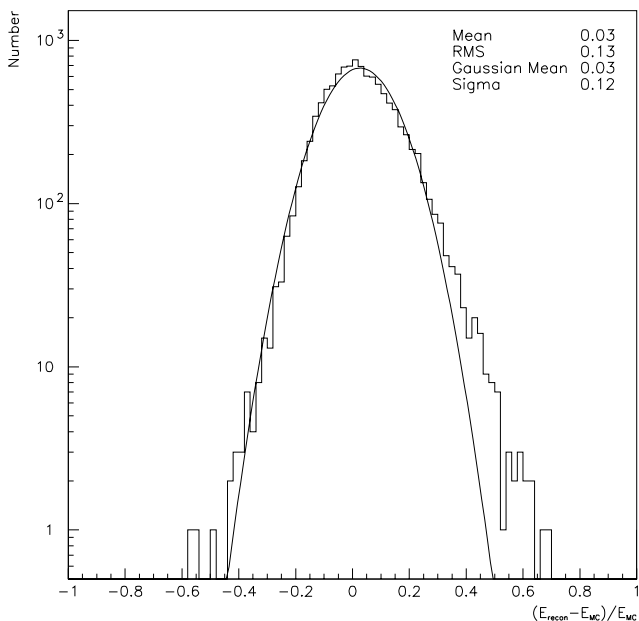


FIG. 5.—Energy resolution of the detector after all cuts, as determined by the detector simulation. E_{MC} is the thrown energy of the shower, and E_{recon} is the reconstructed energy.

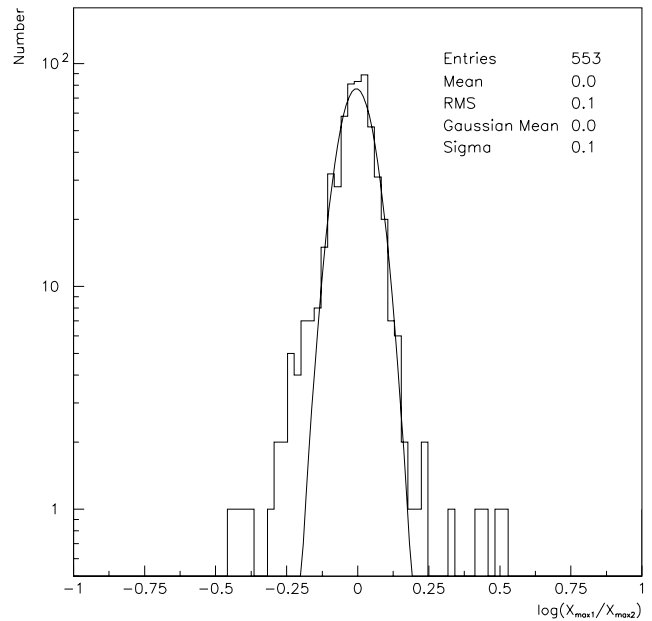


FIG. 6.—Distribution of $\log(X_{\max 1}/X_{\max 2})$ in the data. Compare Fig. 7.

non flashers (Wiencke et al. 1999). One inclined and 10 vertical xenon flashers located between the two HiRes sites are fired every 10 minutes and give important qualitative information about the atmosphere between the sites.

4. DATA ANALYSIS

4.1. Reconstruction

The initial steps in the data-processing chain are documented by Reil (2002) and Abu-Zayyad (2000). First, calibration information is applied to the raw data. The relative timing information from each mirror is then converted to an absolute time as determined by GPS (Wilkinson 1998). The individual mirror triggers are matched to form multiple-mirror events, and the multiple-mirror events from each site are time-matched to build stereo events. To separate noise events from tracklike events, a

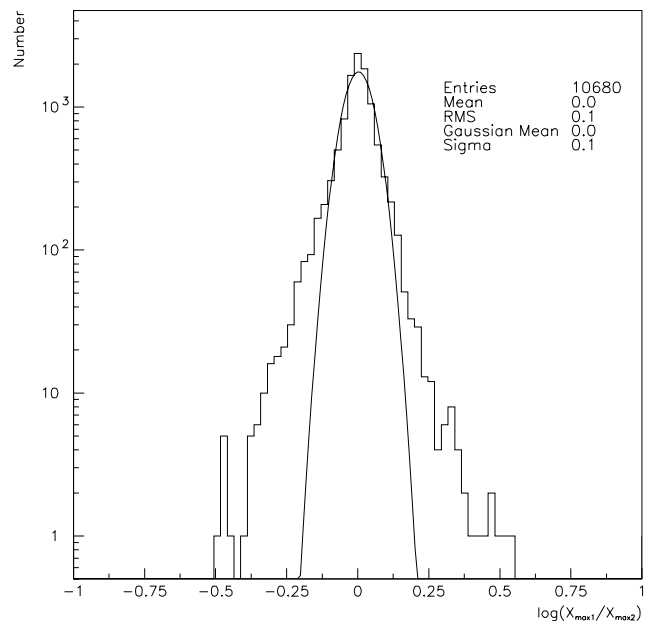


FIG. 7.—Distribution of $\log(X_{\max 1}/X_{\max 2})$ for reconstructed Monte Carlo events. Compare Fig. 6.

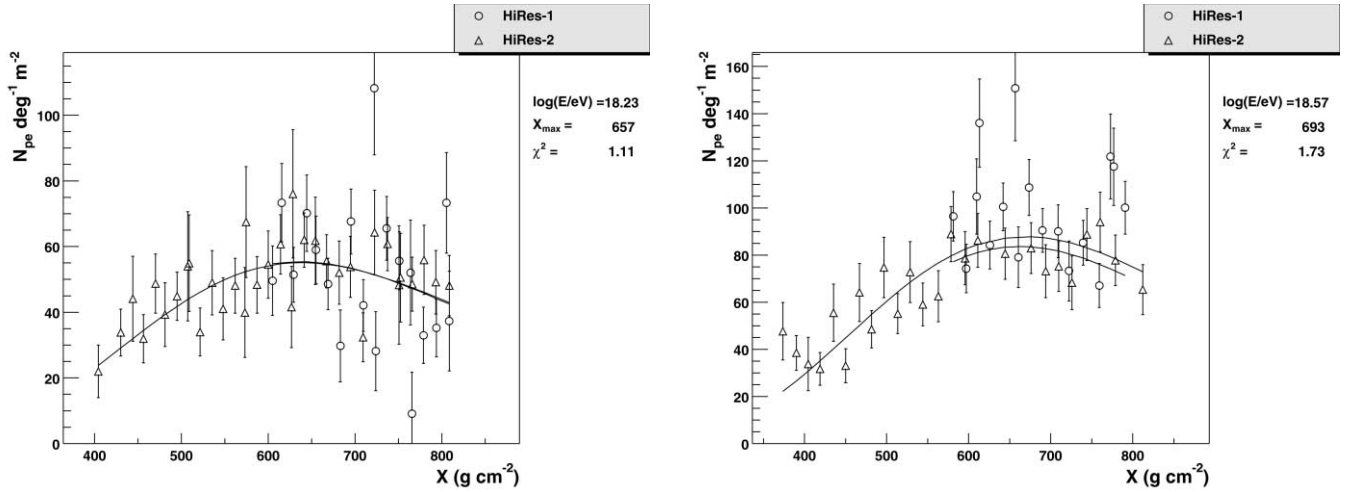


Fig. 8.—Typical reconstructed shower profiles. The solid curve represents the global fit result. R_{p1} and R_{p2} Left, Difference of 0.5%; right, difference of about 5%.

Rayleigh filter is employed (Song 2001). The probability that an event was created by random noise is required to be less than 0.1%.

4.2. Geometry

The axis of the EAS and the position of the detector uniquely define the shower-detector plane (SDP), as illustrated in Figure 1. The location and pointing direction of each PMT cluster have been measured (Bergman et al. 2001; Sadowski et al. 2002), so the pointing direction n_i of each PMT is known and the SDP is easily found.

Once the SDP is known for each site, the intersection of the planes gives the direction and location of the EAS. The next step in the reconstruction is to calculate the shower development profile. However, light arriving at the detector is collected by discrete PMTs, each of which covers about $1^\circ \times 1^\circ$ of the sky. The signal from a longitudinal segment of the EAS is thus necessarily split among many PMTs. For profile fitting, the signal must be recombined into bins that correspond to the longitudinal segments of the EAS. The rebinned signal, corrected for atmospheric extinction and with Cerenkov light subtracted, is fitted to a Gaisser-Hillas functional form,

$$N(X) = N_{\max} \left(\frac{X - X_0}{X_{\max} - X_0} \right)^{(X_{\max} - X_0)/\lambda} \exp\left(\frac{X_{\max} - X}{\lambda} \right). \quad (2)$$

This form has been shown to be in good agreement with EAS simulations (Song 2001; Heck et al. 1998; Kalmykov et al. 1997) and with HiRes data (Abu-Zayyad et al. 2001b).

4.3. Angular Binning

A detailed description of the angular binning technique can be found in Reil (2002) and Archbold (2002). With the incoming photon flux divided into the angular bins, an inverse Monte Carlo method is employed to correct for the nonuniform acceptance of off-axis bins. A Monte Carlo shower with geometry corresponding to the event in question is generated with a Gaisser-Hillas profile (see eq. [2]). Each photon, including both scintillation photons and Cerenkov photons, is individually traced up to the same point where the flux Φ was computed from the data, giving Φ^{MC} . The atmospheric parameters described in § 3 are used to calculate attenuation and scattering. If measured values of horizontal attenuation length and scale height are available in the database for the hour during which the event occurred, those measured values are used. Otherwise, the average atmospheric values are used (Wiencke et al. 2001b). N_{\max} and X_{\max} are then allowed to vary to minimize the χ^2 with respect to the measured flux

$$\chi_{\text{MC}}^2 = \sum_{i=1}^j \frac{(\Phi_i - \Phi_i^{\text{MC}})^2}{\sigma_i^2}, \quad (3)$$

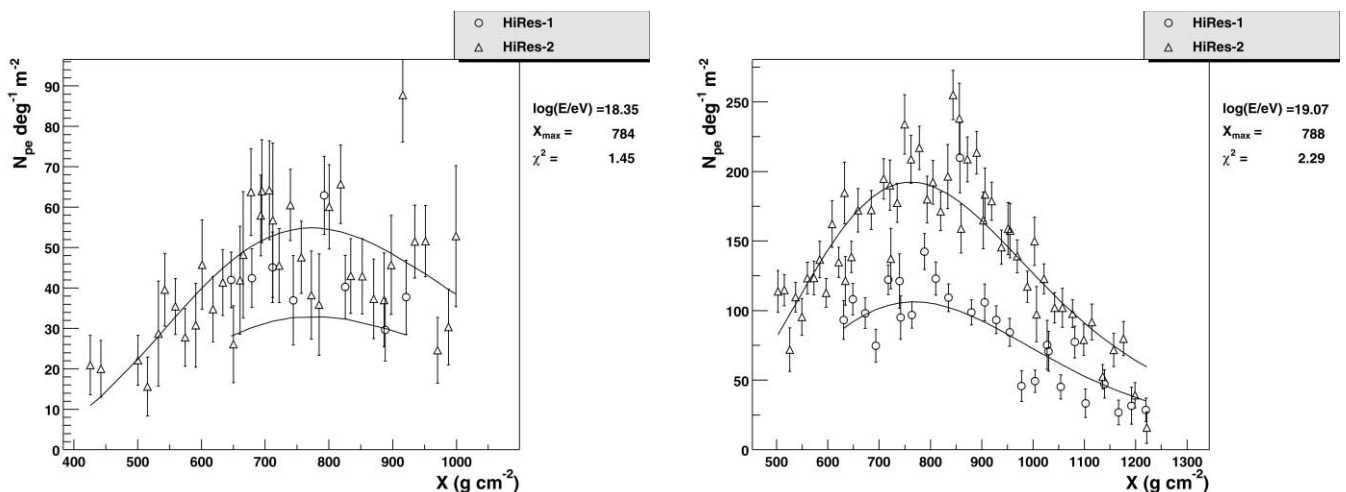


Fig. 9.—Typical reconstructed shower profiles. In both cases, the track was over 20% farther from HiRes-1 than HiRes-2. The solid curve represents the global fit result.

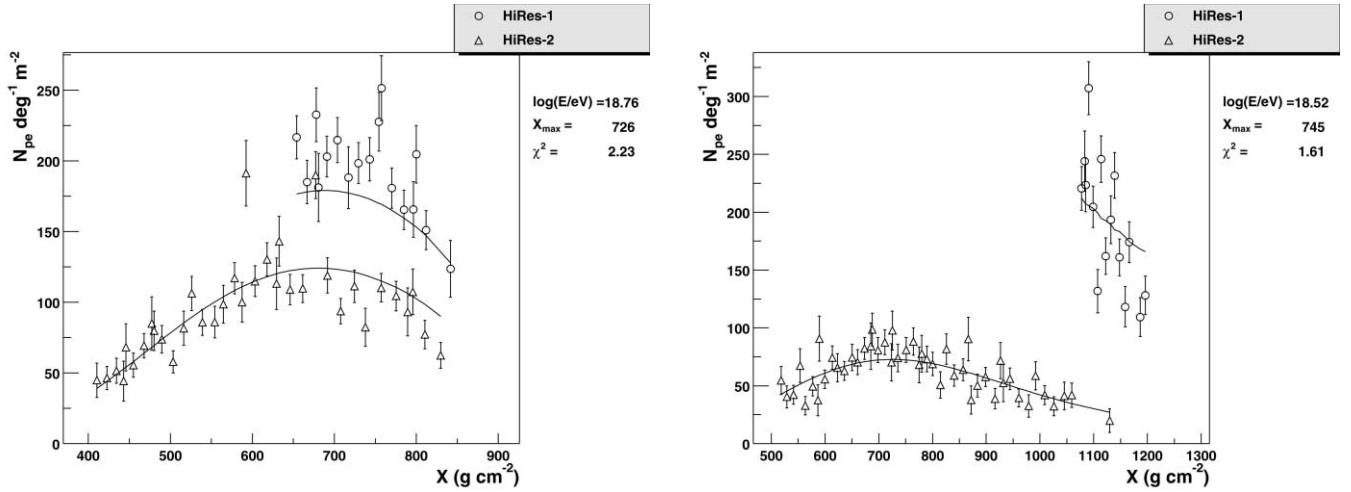


FIG. 10.—Typical reconstructed shower profiles. Even though HiRes-1 observed only a small portion of the shower, the SDP from HiRes-1 stringently constrains the global fit. The energy balance depends in detail on atmospheric corrections. The solid curve represents the global fit result. *Left*: Example for which a perfect balance was not found. However, the measured X_{\max} was unaffected.

where j is the number of bins. For this χ^2 , σ is given by

$$\sigma_i^2 = N_{pe,i}^2 \sigma_{C_{A,eff,i}}^2 + \sigma_{N_{pe,i}}^2 C_{A,eff,i}^2, \quad (4)$$

where N_{pe} is the number of photoelectrons in the bin, $C_{A,eff}$ is a geometric correction factor for nonnormal incidence, and

$$\sigma_{N_{pe,i}}^2 = N_{pe,i} + 40, \quad (5)$$

where 40 (in photoelectrons μs^{-1}) is the average sky noise.

Equation (3) can be minimized for HiRes-1 and HiRes-2 individually or for both sites globally. The N_{\max} and X_{\max} that minimize equation (3) (along with the parameters X_0 and λ) define the shower profile. The total number of charged particles is obtained from the integral of equation (2), and the energy is calculated by multiplying the total number of charged particles by the energy deposited per charged particle. A correction is made for unobserved energy averaging, about 10%.

4.4. Time Binning

In addition to this analysis method, a reconstruction technique that takes advantage of the FADC timing at HiRes-2 has also been developed (Abbasi et al. 2004a). It has the advantage of being less dependent on the details of phototube acceptance. We adapt it to generate one of the quality cuts described below.

In this method, the SDPs are found as above, and the EAS geometry obtained from the intersection of the SDPs is assumed. A first estimate of the number of charged particles at the EAS in each HiRes-2 time bin is calculated assuming all the photons reaching the detector are from air fluorescence. Note that each time bin contains the contributions of a number of PMTs determined by the effective optical spot size. The first guess of the number of charged particles in the shower obtained from the data is compared with the number of charged particles from a Gaisser-Hillas profile. A scan through each X_{\max} and its associated most likely N_{\max} is performed to find the best fit. Cerenkov light is then introduced on the basis of the number of charged particles from the Gaisser-Hillas fit. The Cerenkov light is traced to the detector and subtracted from the signal, and the process is repeated to find a new X_{\max} and N_{\max} . The iteration continues until satisfactory agreement between the predicted data and real data is obtained. The energy of the event is

calculated from the shower profile exactly as in the angular binning technique.

4.5. Stereo Reconstruction Cuts

To ensure that both detectors were working properly, only data files in which at least 20 xenon vertical flasher events (see § 3) were detected at both sites are used for this analysis. We chose events of energy greater than 10^{18} eV because the stereo aperture is rapidly decreasing below this energy. The statistical

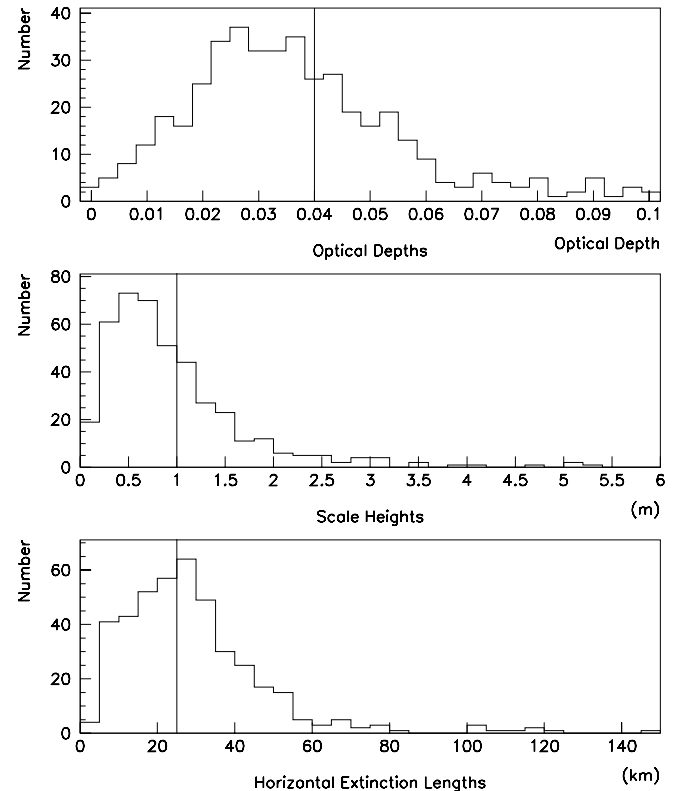


FIG. 11.—Distributions of atmospheric parameters. The vertical lines show the quoted average values, which are pulled to the right by measurements that give optical depths greater than 0.1 and are therefore not shown. If no aerosols were present, the horizontal extinction length would be infinite (Wiencke et al. 2001b).

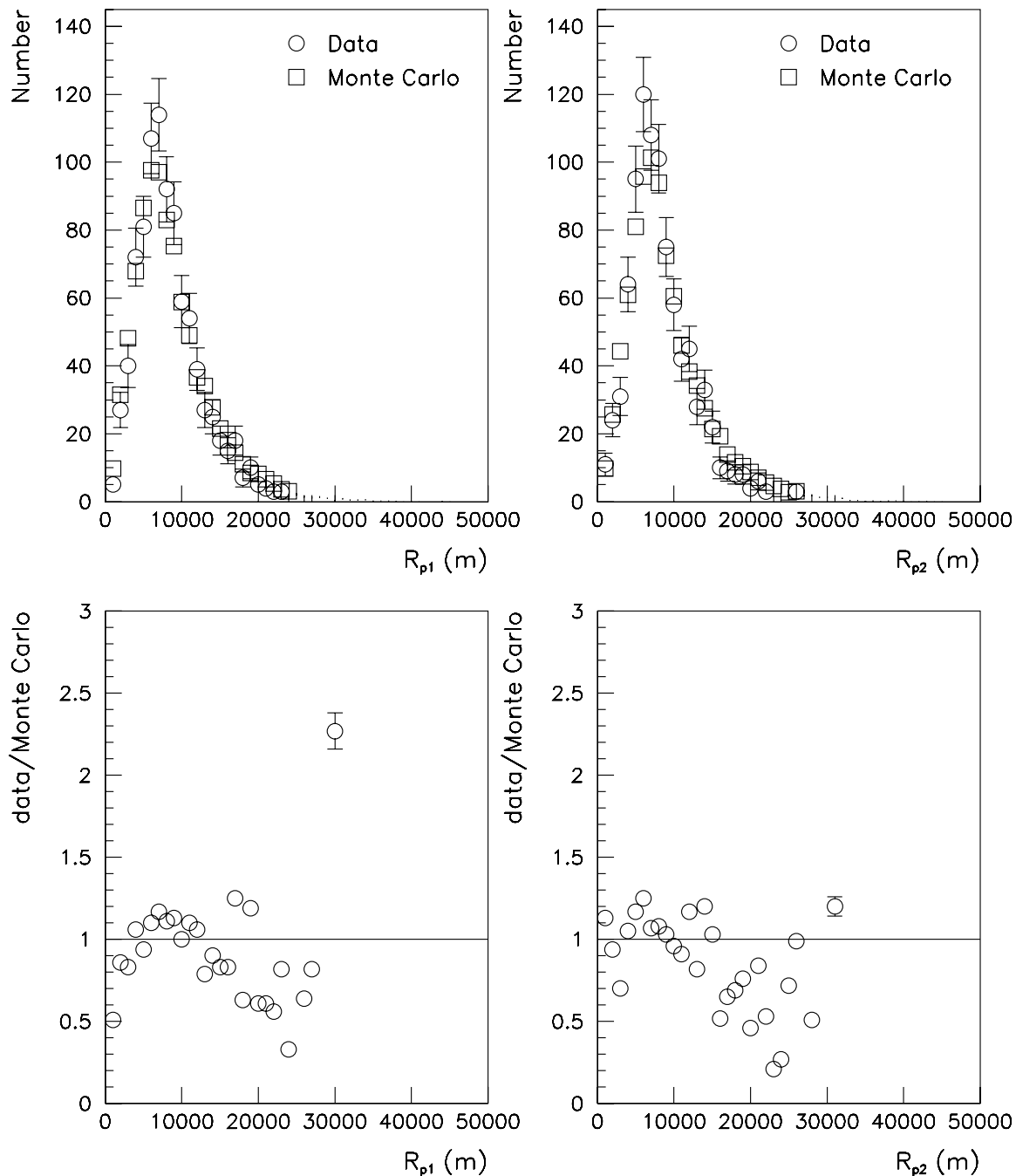


FIG. 12.—Comparison of reconstructed R_p in the data and the Monte Carlo. *Top*, Distributions in the data and the Monte Carlo; *bottom*, ratio of the data to the Monte Carlo in each bin. The similarities of the distributions indicate that the thrown events and the Monte Carlo are excellent representations of the data and the detector, respectively.

reach (defined as at least 4 events per bin) of this sample of data corresponds to a maximum bin at $10^{19.4}$ eV. Additional loose cuts described in Table 1 were used to remove obviously badly reconstructed events and stereo mismatches without biasing the data sample. For the period between 1999 November and 2001 September, 728 events met all the above criteria and were subjected to the atmospheric cuts.

4.6. Atmospheric Cuts

For this analysis, any event with a corresponding VAOD measurement larger than 0.1 was cut. However, because of equipment downtime, the atmosphere was not measured for every hour for which we have data. In that case the operators' comment

log and measurements of laser track length versus width (see § 3) were searched. Periods during which the operators' comments indicated bad weather and/or the length versus width of the laser tracks indicated that the aperture was cloudy were discarded. Of the 553 events composing the final data set, 419 had atmospheric database entries that were used for reconstruction. The remaining 134 events had no database entry but occurred during good weather and were reconstructed with parameters corresponding to average atmospheric conditions.

4.7. Quality Cuts

All remaining events were manually scanned using an event display. The cuts listed in Table 1 produce a data set that contains

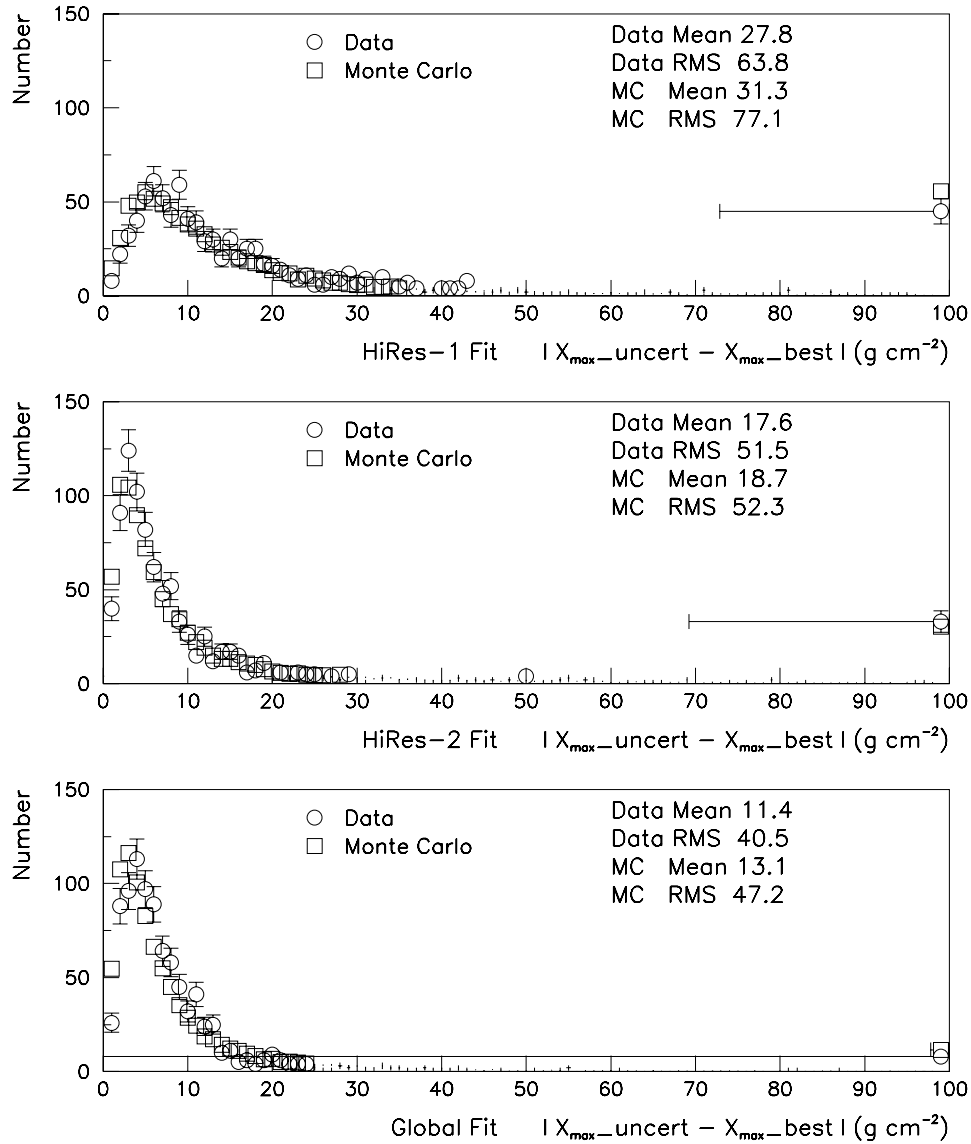


FIG. 13.—Magnitude of X_{\max} error introduced by uncertainty in the SDP, for both the data and Monte Carlo events, where $X_{\max-uncert}$ is the X_{\max} found after the SDP is shifted by the worst-case uncertainty and $X_{\max-best}$ is the X_{\max} using the best SDP. The far right bin in each plot is an overflow bin.

real events during periods of operation when the atmosphere was well understood and the detector was working well. We use the Monte Carlo–simulated data to define these loose cuts to ensure that sufficiently precise determinations of event energy and X_{\max} are obtained. To establish these cuts, a Monte Carlo set of 8341 events was generated with a Fly’s Eye stereo spectrum for these resolution studies. The input for the Monte Carlo was composed of nearly equal numbers of protons and iron nuclei, evenly divided between the QGSJet01 (Kalmykov et al. 1997) and SIBYLL 2.1 (Fletcher et al. 1994; Engel et al. 1999) hadronic interaction models to reflect the extremes of possible composition and hadronic interaction models. Table 1 summarizes the resultant cuts.

Proper reconstruction of the shower profile for events pointed at the detector depends especially on modeling the forward-beamed Cerenkov light and its atmospheric scattering. A minimum viewing angle cut is applied to minimize this problem. The cut on the opening angle between the SDPs is necessary because the geometry obtained by the intersection of the SDPs is not well constrained when the planes are nearly parallel. The Gaisser-Hillas profile can be fitted to HiRes-1 or HiRes-2 data individ-

ually or to both globally. The composition results reported here are from the global fit, whereas the individual fits provide additional quality selection criteria. Events for which χ^2 per degree of freedom for either of the individual fits is larger than 20 are cut. For the global fit, the χ^2 cut is 15.

Events for which the disparity between the individual HiRes-1 and HiRes-2 X_{\max} fits is more than $500\ g\ cm^{-2}$ are discarded. Similarly, each HiRes-2 X_{\max} from the time-binning technique described in § 4.4 is compared with the X_{\max} from the angular binning global fit, and events differing by more than $500\ g\ cm^{-2}$ are cut. Finally, the geometric uncertainty component of the X_{\max} error described in § 6.3 is required to be smaller than $400\ g\ cm^{-2}$ for the individual HiRes-1 and HiRes-2 fits and smaller than $200\ g\ cm^{-2}$ for the global fit. Confidence that the fit to equation (2) found the correct X_{\max} is bolstered when one of the sites sees both the rise toward and fall from X_{\max} . The bracketing cut ensures this by requiring that the measured X_{\max} is no more than $60\ g\ cm^{-2}$ beyond the visible track.

As described below, in addition to the individual measurements of shower X_{\max} from HiRes-1 and HiRes-2 data, a global X_{\max} fit is performed, utilizing all available data. This global fit

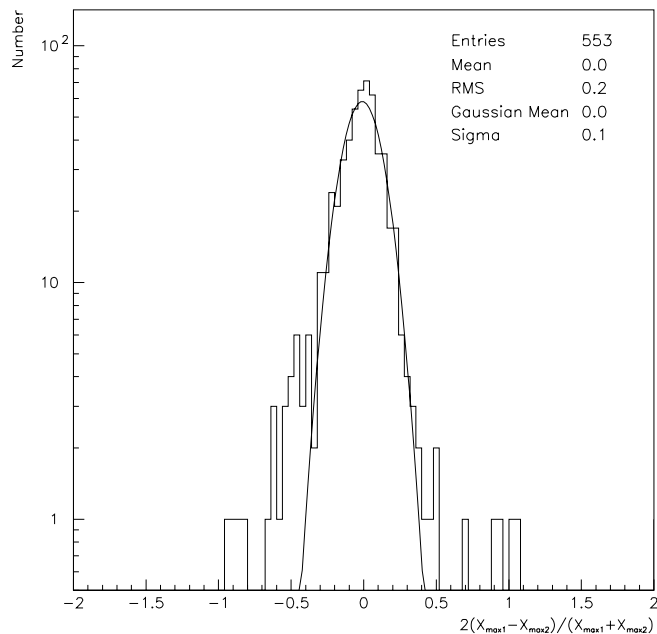


FIG. 14.— X_{\max} pull in the data. The pull is defined as $2(X_{\max 1} - X_{\max 2})/(X_{\max 1} + X_{\max 2})$, where $X_{\max 1}$ and $X_{\max 2}$ are from the individual fits by HiRes-1 and HiRes-2, respectively. Comparison with Fig. 15 shows excellent agreement between the data and Monte Carlo pulls. Both the pull and $\log(X_{\max 1}/X_{\max 2})$ are differences between $X_{\max 1}$ and $X_{\max 2}$ and are statistically equivalent variables, so Fig. 6 is identical to this plot except for a multiplier on the x-axis.

is what is finally used to determine composition. The effect of these cuts on this variable is exemplified by Figure 2, which shows the Monte Carlo global X_{\max} resolution as a function of χ^2 and the cut location. Figure 3 shows the χ^2 distribution for data after all the cuts are applied.

When the above cuts have been made, 553 events survive. The same cuts applied to the Monte Carlo set give a global X_{\max} resolution of 30 g cm^{-2} and an energy resolution of 13%. (See Figs. 4 and 5). Figure 6 shows the distribution of the ratio of $\log(X_{\max 1}/X_{\max 2})$ for the data. The width of this distribution is a measure of the individual X_{\max} resolutions. Because of shorter track lengths in the single ring, the HiRes-1 X_{\max} resolution is estimated to be 1.4 times worse than the HiRes-2 resolution. When we take this and error propagation into account, the width of the distribution in Figure 6 corresponds to a HiRes-2 resolution of about 50 g cm^{-2} , which is in accord with simulations. Figure 7 shows the same distribution for Monte Carlo events. The widths of the distributions are in good agreement. Figs. 8–10 show a representative selection of measured event profiles.

5. EAS SIMULATION

While CR hadronic composition presumably can range anywhere between the two extremes of pure proton and pure Fe, the 30 g cm^{-2} resolution of the detector and the existence of significant shower fluctuations lead us to compare the data with a simplified two-component model. Events are generated using CORSIKA 6.005 and 6.010 (Heck et al. 1998) and using both QGSJet01 (Kalmykov et al. 1997) and SIBYLL 2.1 (Fletcher et al. 1994; Engel et al. 1999) hadronic models for both protons and iron nuclei.

The differences in the hadronic interaction models are evident in the multiplicity, inelasticity, and hadron-air cross section they predict. Each of these directly affects the shower development. The QGSJet multiplicity increases as $\log E$, whereas the multi-

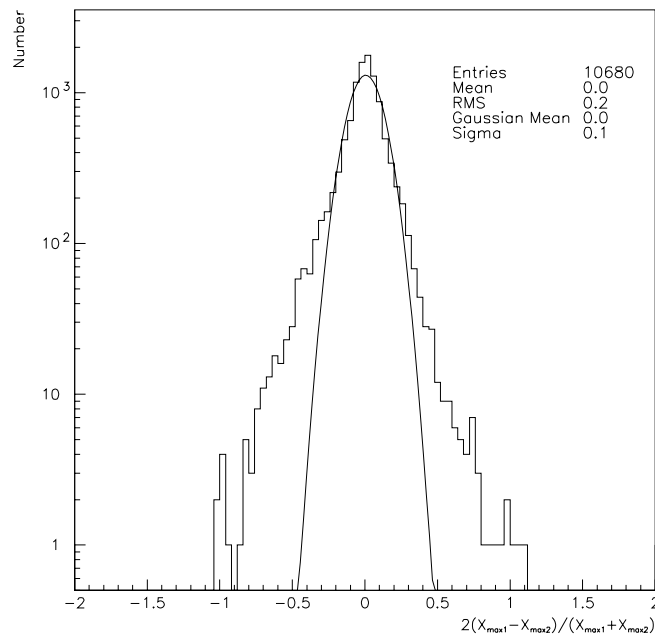


FIG. 15.— X_{\max} Pull for reconstructed Monte Carlo events. The pull is defined as $2(X_{\max 1} - X_{\max 2})/(X_{\max 1} + X_{\max 2})$, where $X_{\max 1}$ and $X_{\max 2}$ are from the individual fits by HiRes-1 and HiRes-2, respectively. Comparison with Fig. 14 shows excellent agreement between the data and Monte Carlo pulls. Both the pull and $\log(X_{\max 1}/X_{\max 2})$ are differences between $X_{\max 1}$ and $X_{\max 2}$ and are statistically equivalent variables, so Fig. 7 is identical to this plot except for a multiplier on the x-axis.

plicity in SIBYLL is below that of QGSJet at relevant energies and rises more slowly than $\log E$ (Heck et al. 2001).

As a result of this multiplicity dependence, QGSJet showers would be expected to develop more quickly than SIBYLL events. Both models show an increase of inelasticity with energy (Kalmykov et al. 1997; Fletcher et al. 1994; Engel et al. 1999), but QGSJet is more inelastic in the UHECR regime (Simpson 2001), again contributing to faster shower development (Heck et al. 2001). However, the hadron-air cross sections in SIBYLL are larger than those of QGSJet at relevant energies. The inelastic proton-air cross section in QGSJet rises approximately linearly with $\log E$, whereas in SIBYLL it rises more rapidly (Heck 2001). The nucleus-air cross sections are comparable in magnitude for both models and rise slowly with energy (Heck 2001; Simpson 2001).

In all simulations, the CORSIKA EGS4 option was selected, enabling explicit treatment of each electromagnetic interaction for particles above a threshold energy. Electrons, positrons, and photons were tracked down to energies of 100 keV. Hadrons and muons were tracked to 300 MeV. All showers were initiated at 45° to the vertical, with sampling at 5 g cm^{-2} of vertical atmospheric depth, giving bins of about 7 g cm^{-2} along the shower.

Because of computational time requirements, simulated UHECR EASs must be generated using a “thinning” approximation (Hillas 1997). Numerous studies have shown that setting the threshold for thinning at 10^{-5} of the energy of the primary reduces computation time without significantly affecting the results in the mean X_{\max} and the ER (Simpson 2001; Song 2001; Hillas 1997; Pryke 2001). The thinning level for this work was set at 10^{-5} .

Iron nucleus-initiated showers are expected to have smaller shower-to-shower fluctuations than proton-initiated showers. Studies with shower generators, including CORSIKA, have shown that generating as few as 200 iron showers at a given energy is sufficient to study primary composition parameters,

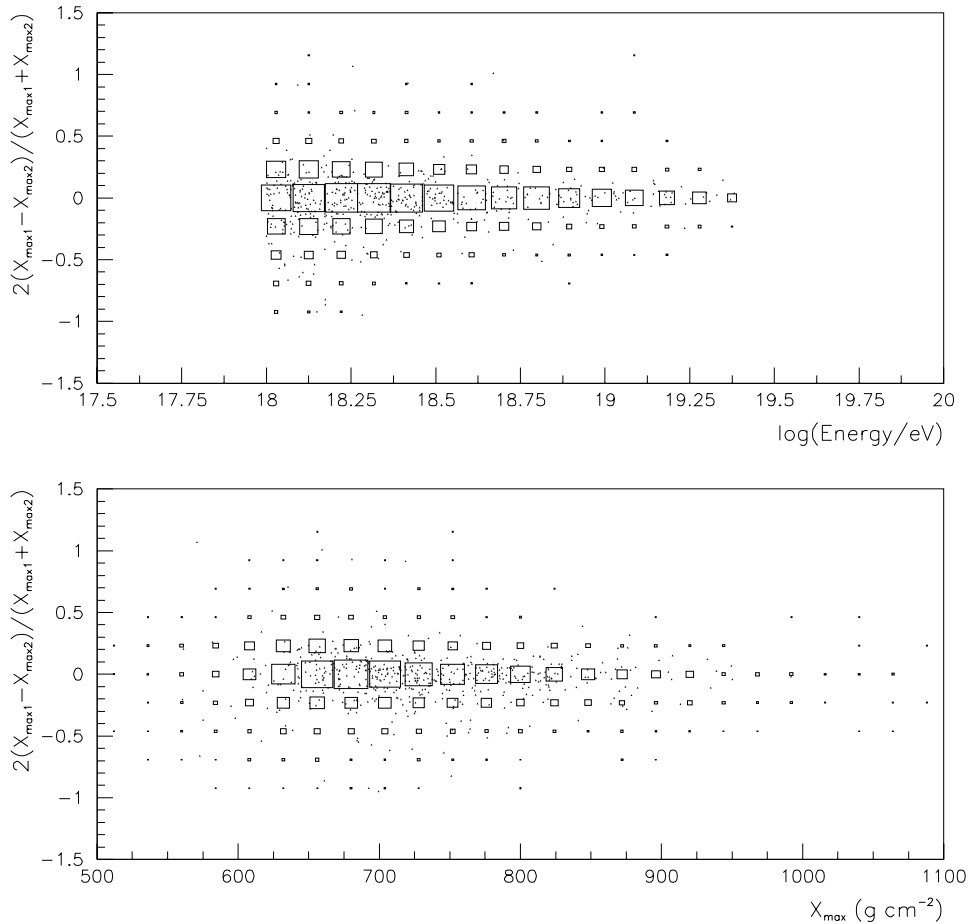


FIG. 16.—Pull as a function of energy and X_{\max} . The boxes represent the Monte Carlo events, and the dots represent the data.

whereas 500 proton showers are needed (Pryke 2001). For this study, at least 400 iron showers and 500 proton showers were generated using each hadronic interaction model in each 0.1 step of $\log E$ from $E = 10^{17.5}$ to 10^{20} eV.

The use of thinning enhances fluctuations near the shower maximum so that choosing the CORSIKA output bin with the largest number of charged particles often yields a significantly incorrect X_{\max} . The input X_{\max} values used here were obtained using a weighted-average smoothing process.

For this work a Monte Carlo library containing the complete profiles (number of charged particles as a function of atmosphere depth) for all 400+ iron showers and 500+ proton showers generated at each energy was constructed. Shower generation in the detector Monte Carlo is accomplished by sampling a shower profile in the library, making no a priori assumption about the shape of the shower profile.

6. DETECTOR SIMULATION

A detailed Monte Carlo simulation of light production, atmospheric transmission, and detector response was developed in conjunction with the reconstruction routines, allowing us to study the reconstruction code's ability to correctly recover information about the primary particle.

6.1. Monte Carlo Program

The full Monte Carlo simulation of a CR event begins with the generation of an EAS. The longitudinal development of each CORSIKA shower is stored in the library described above.

After selecting a primary particle energy from the input spectrum (on the basis of the Fly's Eye stereo spectrum; Baltusaitis et al. 1985), the Monte Carlo randomly selects a shower from the library energy bin closest to the desired energy and interpolates. The zenith angle and distance from the detector are then chosen from random distributions. In each atmospheric depth bin, scintillation light and Cerenkov light are calculated on the basis of the number of charged particles in that bin. The propagation of the light to the detector is then simulated, thus accounting for molecular and aerosol scattering.

The photon flux reaching the detector is distributed among the PMTs by a detailed ray-tracing program that has been checked by examining the point-spread function of stars in the night sky (Bergman et al. 2001; Sadowski et al. 2002). The ray tracing accounts for PMT cluster obscuration of the mirror, mirror shape, mirror reflectivity, and UV filter transmission. Cracks between PMTs are also simulated. A PMT quantum efficiency curve (28% at 355 nm), based on specifications provided by the manufacturers, is used to obtain the number of photoelectrons. A simulated signal is then generated using the gain of the PMT and its preamplifier. The triggering conditions are applied, with the resulting output stored in the same format as real data. The full timing of each Monte Carlo photon, from production at the shower to the PMT face, is stored so that the trigger timing in the output is accurate. The Monte Carlo also simulates noise. Sky noise and electronics noise are added to each signal following a Poisson distribution, and random noise tubes are added to each event with the same mean and σ as in the actual data. The Monte Carlo events are then processed by the same

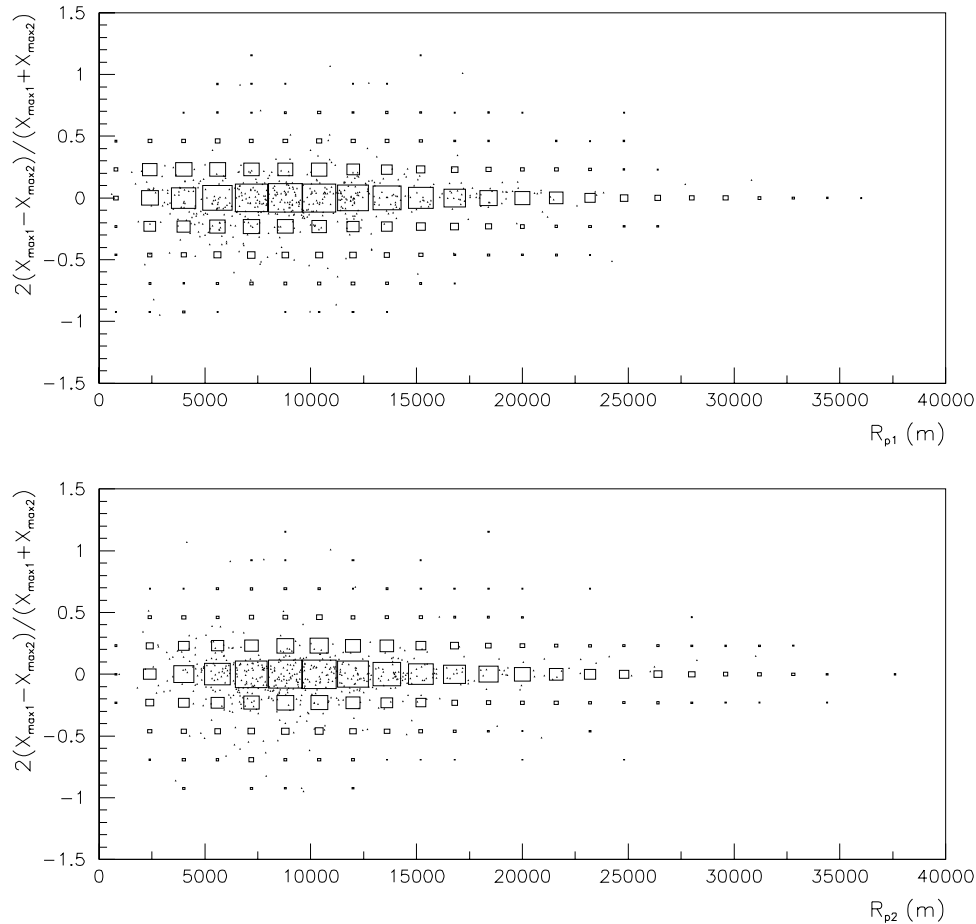


FIG. 17.—Pull as a function of R_p . The boxes represent the Monte Carlo events, and the dots represent the data.

stereo and time-binned reconstruction routines used for the data.

6.2. Atmospheric Comparisons

Real UHECR events occur in whatever atmospheric conditions present themselves in the aperture. Hourly atmospheric parameters are available for most of the data. Figure 11 shows the distribution of atmospheric parameters of ≤ 0.1 (corresponding to the data cut) in the database for VAOD. We use this distribution for thrown events. The mean scale height is inferred from the mean horizontal attenuation length, the mean optical depth, and

$$\text{AOD} = \frac{H_s}{L^a} \quad (6)$$

(Wiencke et al. 2001b).

If no measurement exists in the database, events are reconstructed with the average atmospheric description as discussed above. To simulate the error introduced by this, Monte Carlo events were generated with input atmospheric parameters sampled from the database and then reconstructed with the average parameters. Monte Carlo events were also generated with the average atmospheric parameters. Resolutions after quality cuts using the two sets were indistinguishable.

6.3. Data: Monte Carlo Comparisons

If the Monte Carlo accurately models the detector, then the application of an event selection criterion has the same effect on

the Monte Carlo events and the data. The Monte Carlo can then be used to determine the resolution by reconstructing the Monte Carlo events and comparing the results with the input parameters. In addition, the effects of selection cuts on the resolution can be studied. To determine how well the Monte Carlo models the detector, comparisons were made between more than 20,000 Monte Carlo events and 926 UHECR events.

After applying the cuts described at the beginning of § 4.5, Figure 12 shows the data–Monte Carlo comparisons for the distribution in R_p . The Monte Carlo histogram in the figure represents the results of reconstructing all 20,000+ Monte Carlo events, normalized to have the same area under the curve as the data histogram. The bin-by-bin ratios shown are ratios of the data bin height to the normalized Monte Carlo bin height. Figure 12 is typical of data–Monte Carlo comparisons in other variables such as energy, zenith angle, ψ , track length in degrees and g cm^{-2} , and maximum single $N_{pe} \text{ deg}^{-1} \text{ m}^{-2}$ in each event. Good agreement between the data and the Monte Carlo is found in all cases.

An accurate profile determination depends on an accurate geometry. The SDP-finding routine returns the normal to the SDP, as well as the uncertainties in each component of the normal. For each event, the worst-case error in each SDP was propagated through the reconstruction to give the uncertainty in X_{max} due to the uncertainty in geometry. Figure 13 shows the distribution of these uncertainties for X_{max} in the data and the Monte Carlo, again showing good agreement.

Since we compare the data and the Monte Carlo to extract the CR composition, it is vital that the Monte Carlo accurately

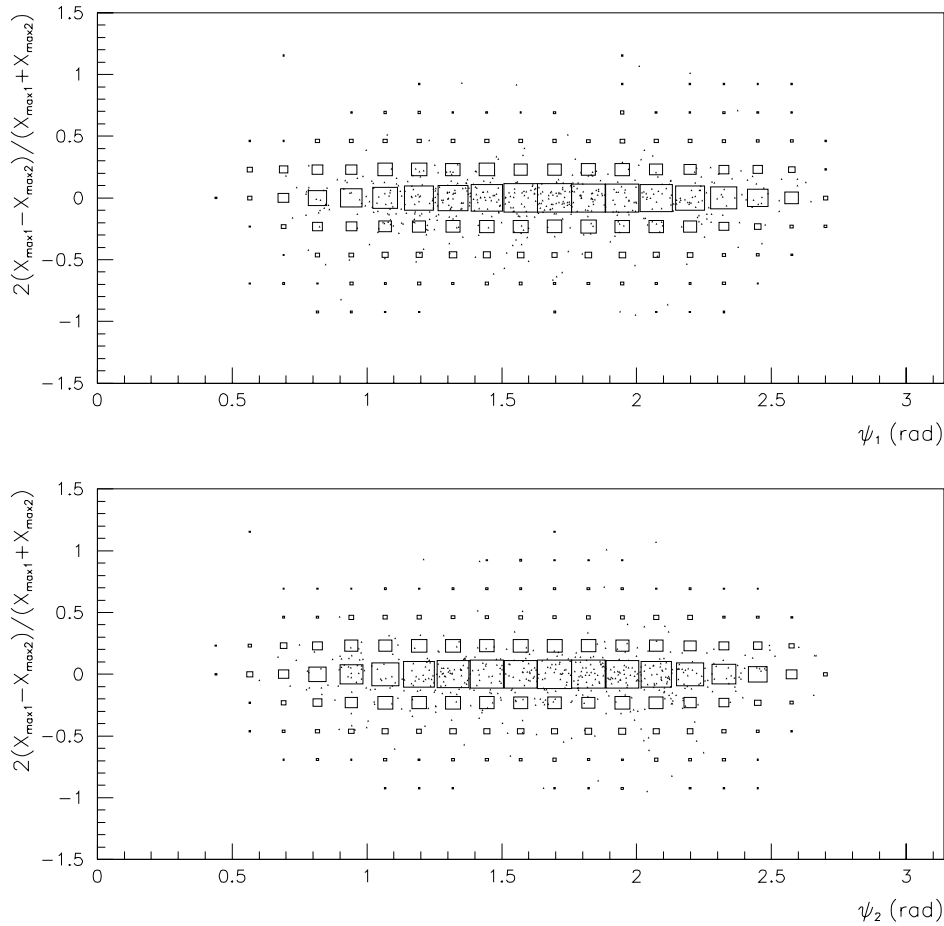


FIG. 18.—Pull as a function of ψ . The boxes represent the Monte Carlo events, and the dots represent the data.

reproduce the detector and reconstruction resolution. This can be demonstrated by examining the differences in the individual detector fits. Figures 14 and 15 show the pull, defined as $2(X_{\max 1} - X_{\max 2}) / (X_{\max 1} + X_{\max 2})$, where $X_{\max 1}$ and $X_{\max 2}$ are from the individual fits by HiRes-1 and HiRes-2, respectively, after all cuts. The nearly Gaussian shape of the pull and the nearly identical pull distribution for the Monte Carlo and the data show that the Monte Carlo resolution represents the real detector resolution well. In addition, Figures 16–18 show the dependence of the data and Monte Carlo pull on X_{\max} , E , R_p , and the ψ angles. There is excellent agreement between the data and the Monte Carlo and no significant dependence of the pull on any of these variables. Although the data pull distribution cannot be directly used to obtain the global X_{\max} resolution, the excellent agreement between data and Monte Carlo pulls implies that the Monte Carlo estimate of the global X_{\max} resolution is reliable.

7. ELONGATION RATE RESULT

The data were binned in energy as shown in Table 2. The statistical errors are the standard error of the mean.

Figure 19 shows the ER result. The QGSJet and SIBYLL model predictions and the HiRes Prototype result are also indicated. The measured ER is $54.5 \pm 6.5 \text{ g cm}^{-2}$ per decade (statistical uncertainty only; see § 7.1) compared with the model predictions of 50 and 61 g cm^{-2} per decade for QGSJet protons and iron nuclei, respectively, and 57 and 59 g cm^{-2} per decade for SIBYLL protons and iron nuclei, respectively, as well as

with the HiRes Prototype result of $93.0 \pm 8.5(\text{stat}) \pm 10.5(\text{sys}) \text{ g cm}^{-2}$ per decade.

7.1. Systematic Uncertainty in Elongation Rate

Uncertainties in energy do not have a large effect on ER because of the logarithmic energy scale. Any systematic uncertainty

TABLE 2
ELONGATION RATE DATA

log E Bin	Number of Events	Mean log E	Mean X_{\max} (g cm^{-2})
18.0–18.1	92	18.05 ± 0.01	711.3 ± 8.2
18.1–18.2	79	18.15 ± 0.01	709.2 ± 7.5
18.2–18.3	82	18.25 ± 0.01	714.5 ± 9.3
18.3–18.4	74	18.35 ± 0.01	729.8 ± 8.4
18.4–18.5	59	18.45 ± 0.01	744.8 ± 8.5
18.5–18.6	34	18.55 ± 0.01	751.1 ± 11.3
18.6–18.7	29	18.65 ± 0.01	734.2 ± 11.2
18.7–18.8	23	18.74 ± 0.01	752.2 ± 14.1
18.8–18.9	23	18.86 ± 0.01	752.3 ± 8.9
18.9–19.0	20	18.94 ± 0.01	757.0 ± 11.4
19.0–19.1	13	19.05 ± 0.01	758.9 ± 18.0
19.1–19.2	14	19.17 ± 0.01	764.4 ± 7.7
19.2–19.3	6	19.26 ± 0.01	781.6 ± 9.8
19.3–19.4	5	19.35 ± 0.01	796.2 ± 27.7

NOTE.—The uncertainties are the standard error of the means. In log E , E is in electron volts.

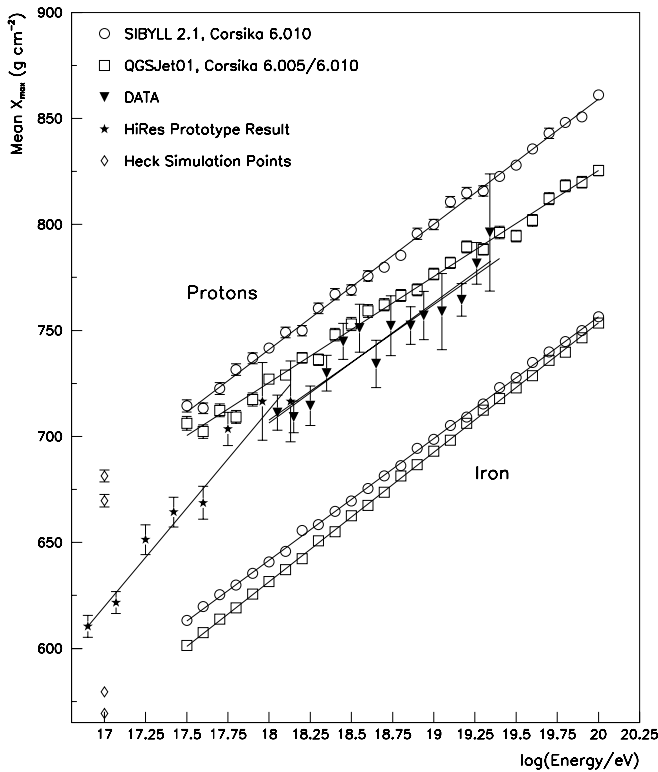


FIG. 19.—ER result. The predictions for QGSJet and SIBYLL protons and iron are shown for comparison. The stars show the HiRes Prototype result. The diamonds show simulation points calculated by Heck. The best fit to the data and a fit to the 76% of the events that have hourly atmospheric corrections are shown. The latter has a slightly steeper slope.

in X_{\max} that applies over the entire energy range changes the absolute value of X_{\max} but does not change the ER. To affect the ER, the systematic uncertainty must shift X_{\max} in an energy-dependent way.

As discussed in § 3, the measured average atmosphere at HiRes is parameterized by a VAODof 0.04 ± 0.02 (sys). Because the database used to obtain this result was used in the reconstruction of about three-quarters of the events, the statistical variation about this mean is already represented in the data and the Monte Carlo. The effect of the systematic error on the mean is studied by reprocessing the data with a dirtier atmosphere. Just as in the original processing, the atmospheric database was sampled and either the database entry or the standard atmosphere was used, as appropriate. Since horizontal extinction is measured separately but the scale height is inferred, for each event the aerosol scale height was increased such that the optical depth was increased by 0.02. The dominant effect of the dirtier atmosphere was to increase the reconstructed energies. The reconstructed X_{\max} values also decreased slightly, with the two effects combining to steepen the ER, as shown in Figure 20. Because the energy scale is logarithmic, the introduced change in the ER is small. Since 24% of the data was reconstructed using an average atmosphere, we check that deleting this part of the data does not significantly affect our value for the ER. This is shown in Figure 19.

The modeling of the Cerenkov beam in the reconstruction program can introduce an energy-dependent uncertainty in X_{\max} . Whereas the absolute intensity of Cerenkov radiation is well known, the effective angular distribution in an EAS depends on the multiple scattering of electrons in the atmosphere, which has some uncertainties. To investigate this, the reconstruction code

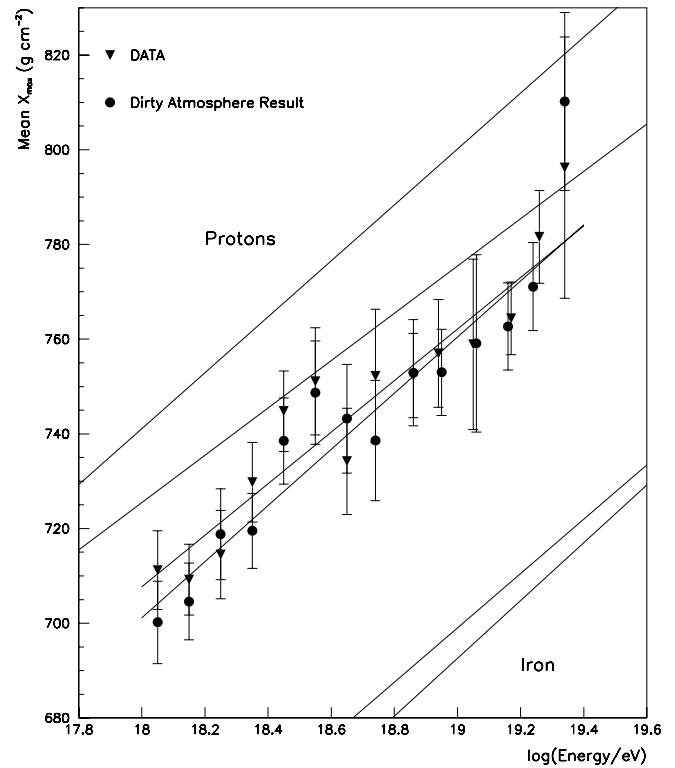


FIG. 20.—Uncertainty in ER. The circles are obtained by reprocessing the data with a dirtier atmosphere. The x - and y -axes are expanded relative to Fig. 19 to accentuate the small difference. The top two and bottom two lines are the model predictions.

was modified to make the modeled EAS Cerenkov beam 2° wider (consistent with 1σ errors in previous measurements), and the data were reprocessed. The ER was essentially unchanged.

8. X_{\max} DISTRIBUTION WIDTH RESULT

Protons are expected to show more shower-to-shower fluctuation than iron nuclei. Figure 21 shows that at each of the three energies, both QGSJet and SIBYLL predict that the distribution of X_{\max} is wider for proton showers than for iron showers. Thus, if the composition changes from Fe to protons as energy increases, for example, then the X_{\max} distribution at lower energies is significantly narrower than at higher energies. Figure 22 shows the X_{\max} distributions expected from a purely light or a purely heavy flux with a Fly's Eye stereo spectrum over the entire energy range of interest. For both hadronic interaction models the difference between iron nuclei and protons is clear even over this large energy range.

Figures 23–26 show the width of the X_{\max} distribution. The histograms representing the Monte Carlo in Figures 23–26 were obtained by taking over 4500 showers for each model through the complete Monte Carlo and reconstruction routines, subject to the same cuts as the data. Nearly 2500 events of each type survived. The areas of the Monte Carlo histograms are normalized to the area of the data histogram.

For Figures 23 and 24, the data were divided into two energy bins selected such that each contained about half the events. The data show that the width is not changing with energy, indicating that composition is constant or only slowly changing. The width of the data distribution in Figures 25 and 26 indicates that the composition is predominantly light, in agreement with the ER interpretation. These figures also show the contribution of the 24% of the data reconstructed with an average atmosphere. There

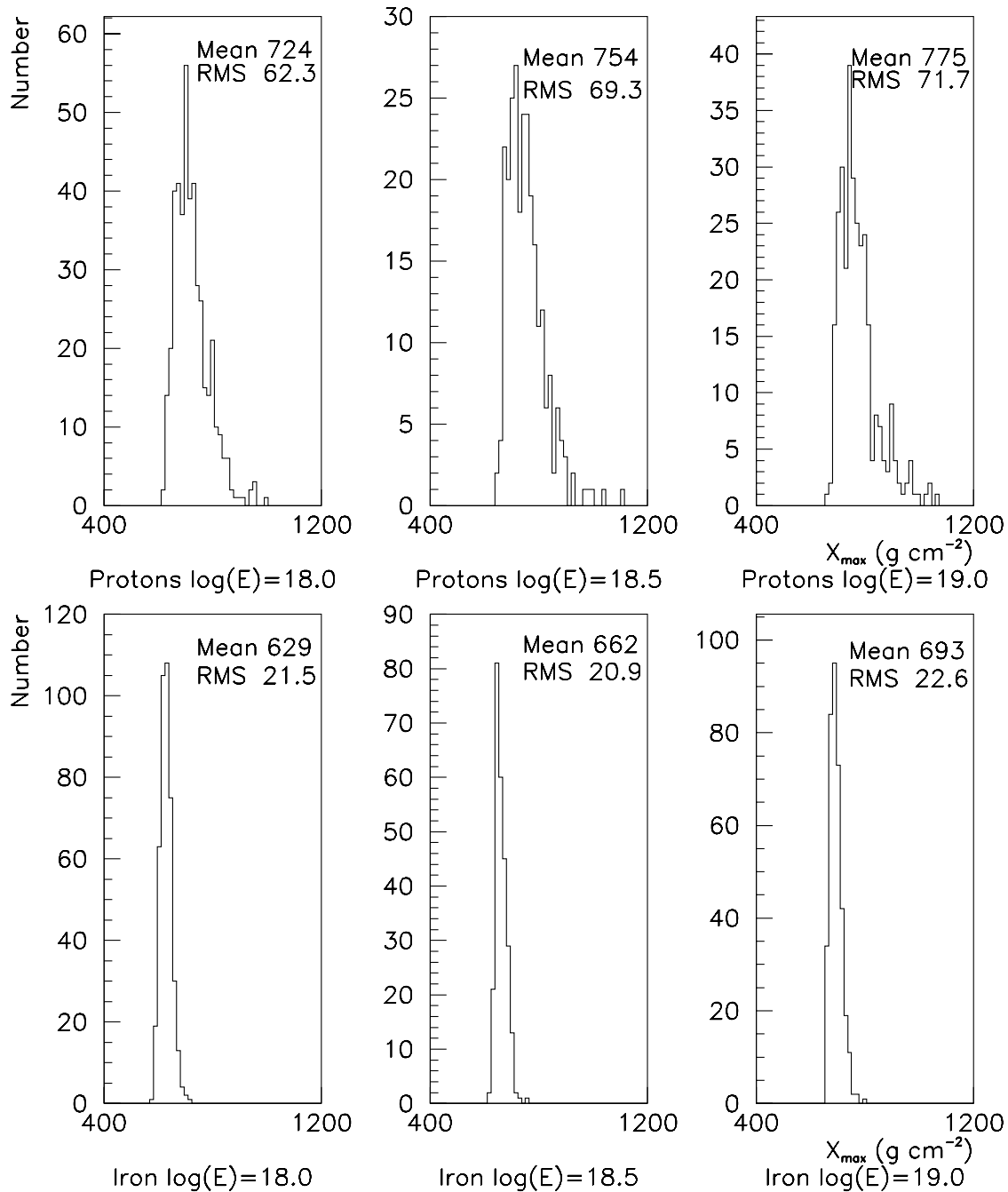


FIG. 21.— X_{\max} distributions from CORSIKA for primary UHECR energies of $10^{18.0}$, $10^{18.5}$, and $10^{19.0}$ eV. At each energy, the iron distribution is much narrower than the proton distribution.

is no statistically significant difference between this sample and the total data sample.

Figures 25 and 26 show that the data are consistent with a nearly purely protonic composition, especially when compared with the QGSJet model. If we assume a simple two-component model in which the primary flux is a mixture of protons and iron nuclei, Figure 27 shows how well the model fits the data as a function of the fraction of protons. The best fits are at 80% protons for QGSJet and 60% for SIBYLL. Figure 27 also shows the models compared with the data.

9. SYSTEMATIC UNCERTAINTY IN ABSOLUTE VALUE OF X_{\max}

Figure 27 suggests that the composition of UHECRs is predominantly light above 10^{18} eV. However, systematic errors

in the absolute value of X_{\max} could artificially move the measured X_{\max} values too deep in the atmosphere. The X_{\max} values for events with energies above 10^{19} eV are of particular interest. Potential contributors to the systematic uncertainty in X_{\max} are biases introduced by reconstruction, errors in PMT pointing directions, variations of the molecular and aerosol component of the atmosphere, and incorrect treatments of the Cerenkov beam.

Resolution studies (Figs. 2 and 3) show that the mean of the reconstructed X_{\max} distribution differs by 5 g cm^{-2} from the input value. For events with energy greater than 10^{19} eV, the mean of the distribution shifts by 3 g cm^{-2} . The phototube cluster pointing directions have been confirmed by observing stars (Bergman et al. 2001; Sadowski et al. 2002). The largest deviation of the true pointing direction from the direction used

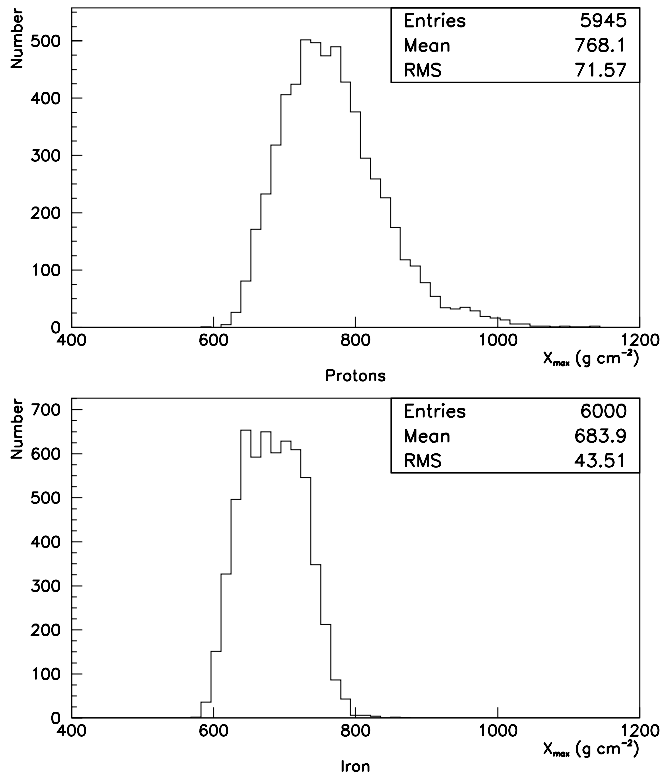


FIG. 22.— X_{\max} distributions from CORSIKA for primary UHECRs with energies between $10^{18.0}$ and $10^{19.4}$ eV.

in reconstruction is 0.3. This corresponds to a maximum X_{\max} error of 15 g cm^{-2} . The molecular component of the atmosphere may be different from the US Standard Atmosphere (NOAA 1976) assumed in the reconstruction. The variations in the atmosphere as measured by radiosondes launched from the Salt

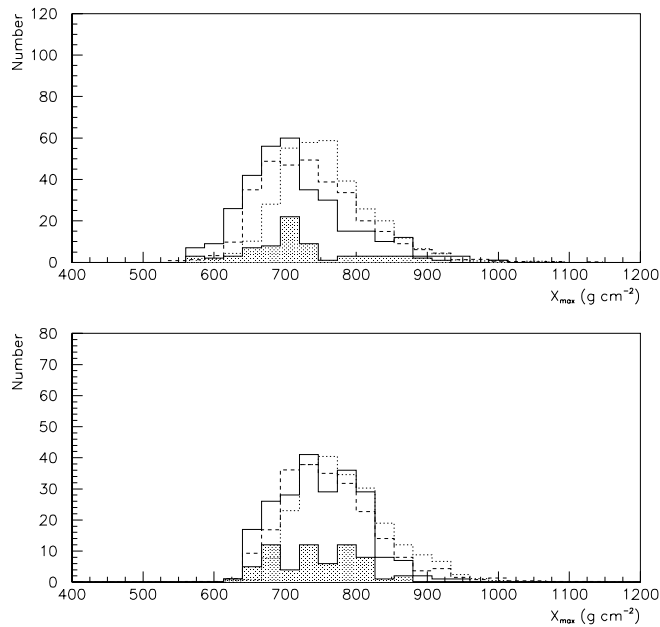


FIG. 23.—Distribution width results for protons, showing the data (solid line), the 24% of the events reconstructed with the average atmosphere (shaded area), the QGSJet model (dashed line), and the SIBYLL model (dotted line). Top, Plot for $\log E = 18.0-18.4$, where E is in electron volts; bottom, plot for $\log E = 18.4-19.4$, where E is in electron volts. Compare Figs. 21 and 24.

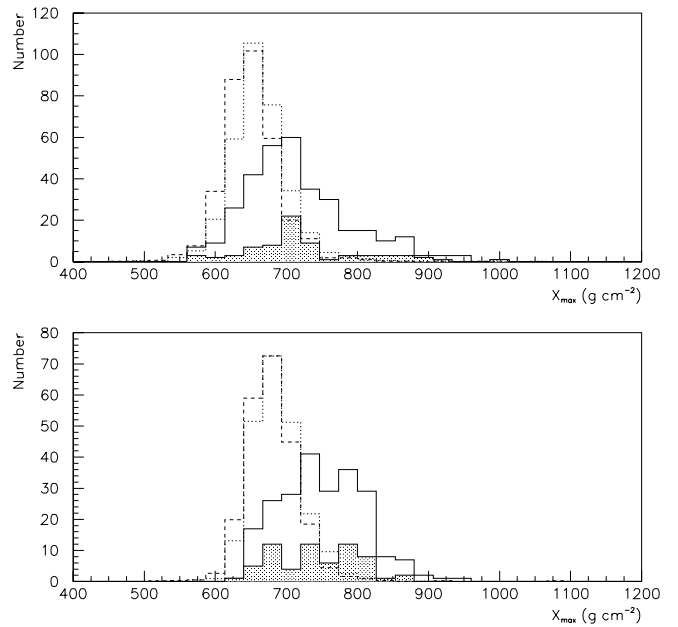


FIG. 24.—Distribution width results for iron, showing the data (solid line), the 24% of the events reconstructed with the average atmosphere (shaded area), the QGSJet model (dashed line), and the SIBYLL model (dotted line). Top, Plot for $\log E = 18.0-18.4$, where E is in electron volts; bottom, plot for $\log E = 18.4-19.4$, where E is in electron volts. Compare Figs. 21 and 23.

Lake City airport has been studied (Martin et al. 1999). In the month of the year that varied most from the standard model, the actual pressure differed from that of the model by 8%, which leads to a 10 g cm^{-2} difference in integrated atmospheric depth. Subsequent studies by Y. F. of radiosonde data over several years have confirmed this initial study. Using an incorrect atmospheric attenuation could distort the shower profile and systematically shift the position of X_{\max} . Figure 20 shows that above 10^{19} eV, an increase as large as 0.02 in VAOD (a 50%

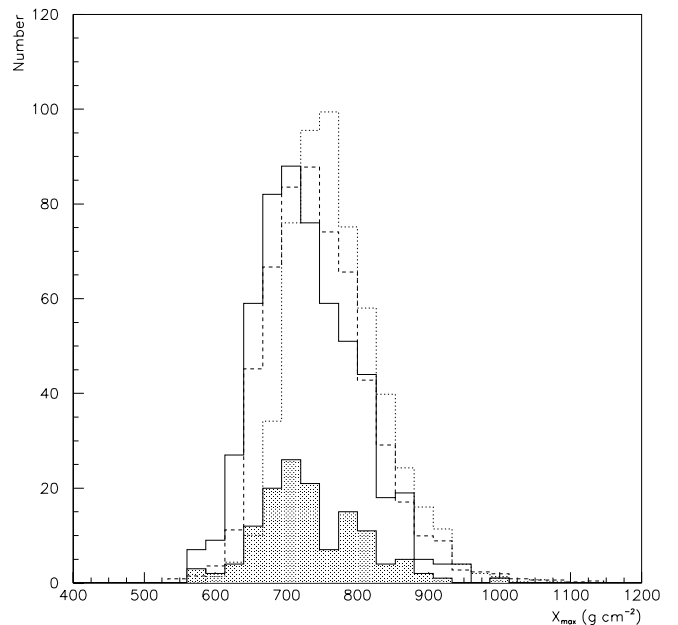


FIG. 25.—All-energy distribution width result, for protons, showing the data (solid line), the 24% of the events reconstructed with the average atmosphere (shaded area), the QGSJet model (dashed line), and the SIBYLL model (dotted line). Compare Figs. 22 and 26.

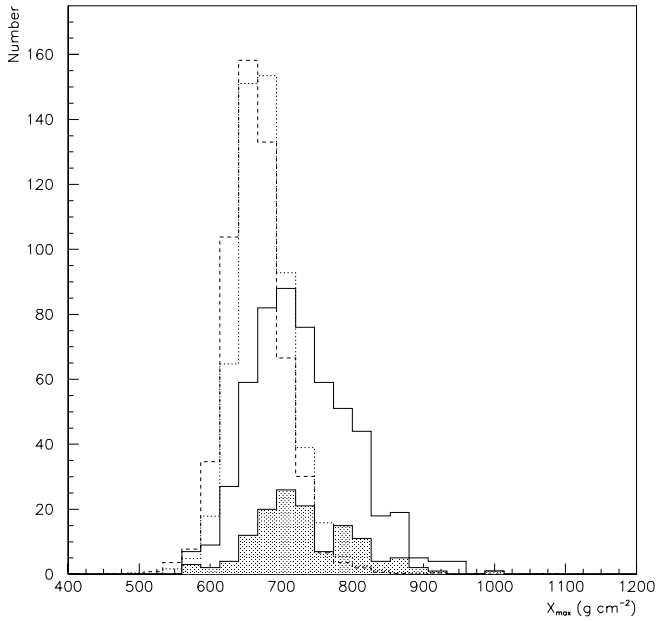


FIG. 26.—All-energy distribution width result for iron, showing the data (solid line), the 24% of the events reconstructed with the average atmosphere (shaded area), the QGSJet model (dashed line), and the SIBYLL model (dotted line). Compare Figs. 22 and 25.

change) does not significantly change the mean values of X_{\max} . As described in § 7.1, the data were reprocessed with a larger value of the Cerenkov beam width. The mean difference between the X_{\max} obtained from reconstruction with the standard Cerenkov beam width and the X_{\max} obtained by using a wider beam is less than 1 g cm^{-2} and is negligible.

Table 3 summarizes the systematic uncertainties in X_{\max} for energies above 10^{19} eV . Adding the individual uncertainties in quadrature gives an overall systematic uncertainty of less than 20 g cm^{-2} . This is less than the detector resolution and much

TABLE 3
SYSTEMATIC UNCERTAINTIES IN X_{\max}

Uncertainty	Value (g cm^{-2})
Pointing direction.....	15
Atmospheric variations.....	10
Reconstruction bias.....	5
Sum in quadrature.....	18.7

less than the 75 g cm^{-2} difference between the proton and iron mean X_{\max} values.

10. CONCLUSIONS

The measured ER result is consistent with a constant or slowly changing composition between $10^{18.0}$ and $10^{19.4} \text{ eV}$. The data are also in very good agreement with the HiRes Prototype data in the region where they nearly overlap. The HiRes Prototype results showed a composition change from heavy to light in the 10^{17} – 10^{18} eV range, but the HiRes data do not show a continuation of this ER. This can be interpreted as strong evidence for a transition from a heavy composition to a predominantly light and constant or only slowly changing composition above 10^{18} eV . The earlier Fly’s Eye stereo data also show a transition from a heavy to a light composition, although with a broader transition region in energy. This is consistent with the present data if the systematic errors and worse X_{\max} resolution quoted in that work are taken into account (R. U. Abbasi et al. 2005, in preparation).

In the present study, the widths of the X_{\max} distributions in the UHECR regime strengthen this conclusion. Such a transition is interesting in the light of reported structure in the UHECR spectrum in the same energy region. Many experiments have seen evidence for a second knee in the middle of the 10^{17} th decade and an ankle structure near $3 \times 10^{18} \text{ eV}$. The change in composition may reflect a change from a dominant Galactic CR flux to

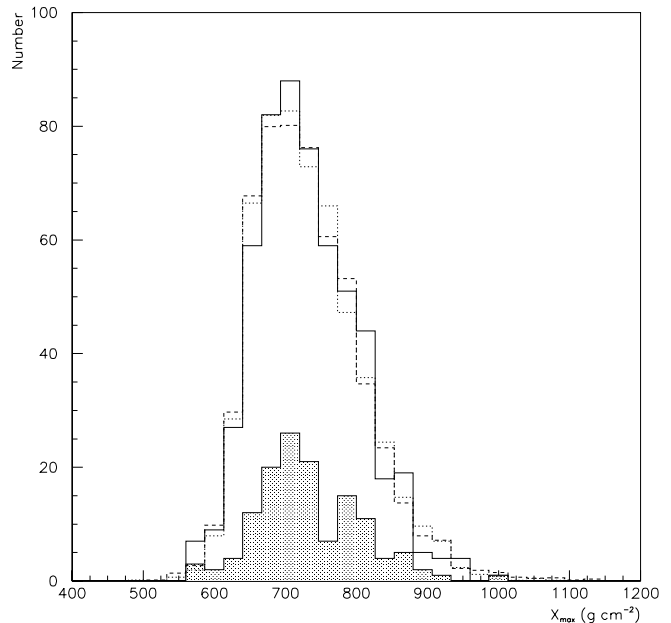
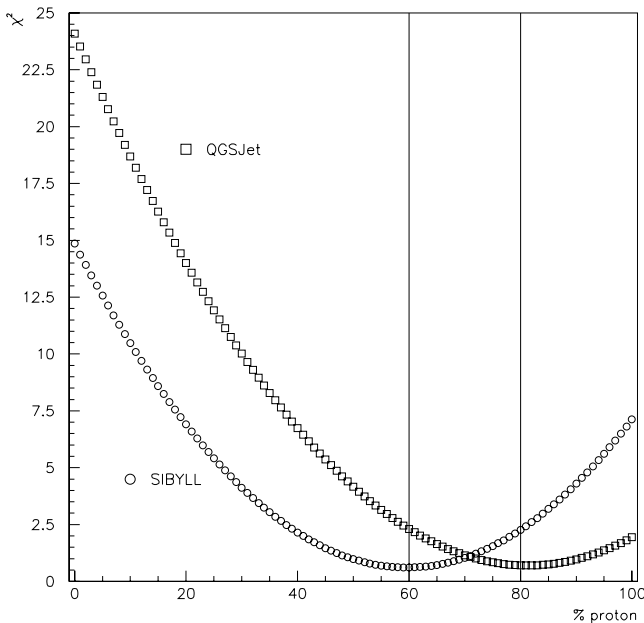


FIG. 27.—Simple two-component composition model fit results. Left, χ^2 for a comparison of the model with the data as a function of the fraction of protons (data points); right, data (solid line), the 24% of the events reconstructed with the average atmosphere (shaded area), the QGSJet model with 77% protons (dashed line), and the SIBYLL model with 57% protons (dotted line).

an extragalactic flux that dominates near 10^{19} eV. Observation of anisotropy from the Galactic plane would support this picture. Some evidence for such anisotropy has been reported (Bird et al. 1999; Hayashida et al. 1999; Bellido et al. 2001).

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